

1 Newton 法

Let f_i be the i -th element of a column vector f . f_i is a function of n variables $(x_1, \dots, x_n)$. x and α be column vectors. We have

$$f_i(x) = f_i(\alpha) + \sum_j \frac{\partial f_i}{\partial x_j}(\alpha)(x_j - \alpha_j) + \frac{1}{2} \sum_{j,k} \frac{\partial^2 f_i}{\partial x_j \partial x_k}(\alpha)(x_j - \alpha_j)(x_k - \alpha_k) + O((x - \alpha)^3) \quad (1)$$

where $O((x - \alpha)^3) = \sum_{n, |n|=3} O(\prod_i (x_i - \alpha_i)^{n_i})$. Since $|x|^2 < \varepsilon^2$ implies $|x_i|^2 < \varepsilon^2$, $O((x - \alpha)^3) \leq O(|x - \alpha|^3)$.

次が Newton 法の式.

$$\text{Jac}(f)(x(n))(x(n+1) - \alpha) = \text{Jac}(f)(x(n))(x(n) - \alpha) - f(x(n)) \quad (2)$$

ベクトルの場合の Newton 法を証明するために、ベクトルの i 番目の成分を考える. It follows from (1) that

$$f_i(x(n)) = f_i(\alpha) + \sum_j \frac{\partial f_i}{\partial x_j}(\alpha)(x(n)_j - \alpha_j) + \frac{1}{2} \sum_{j,k} \frac{\partial^2 f_i}{\partial x_j \partial x_k}(\alpha)(x(n)_j - \alpha_j)(x(n)_k - \alpha_k) + O((x(n) - \alpha)^3) \quad (3)$$

$$\text{Jac}(f)(x)_{ij} = \frac{\partial f_i}{\partial x_j}(\alpha) + \sum_k \frac{\partial^2 f_i}{\partial x_j \partial x_k}(\alpha)(x_k - \alpha_k) + O(|x - \alpha|^2). \quad (4)$$

$\text{Jac}(f)(x(n))(x(n) - \alpha)$ の i 成分は

$$\sum_j \text{Jac}(f)(x(n))_{ij}(x(n)_j - \alpha_j)$$

なので、上の展開を代入すると

$$\sum_j \frac{\partial f_i}{\partial x_j}(\alpha)(x(n)_j - \alpha_j) + \sum_{k,j} \frac{\partial^2 f_i}{\partial x_j \partial x_k}(\alpha)(x(n)_k - \alpha_k)(x(n)_j - \alpha_j) + O(|x - \alpha|^3). \quad (5)$$

2 次のところに $1/2$ がないことに注意.

(2) の右辺は (5) 引く (3). その i 成分は、2 次の係数が 1 と $1/2$ なので

$$O(|x(n) - \alpha|^2).$$

Jacobian の冪級数展開を考えて (todo)

$$\text{Jac}(f)(x(n))^{-1} = \text{Jac}(f)(\alpha)^{-1} + O(|x(n) - \alpha|)$$

よって

$$x(n+1) - \alpha = (\text{Jac}(f)(\alpha)^{-1} + O(|x(n) - \alpha|)) O(|x(n) - \alpha|^2) \quad (6)$$

つまり

$$|x(n+1) - \alpha| = O(|x(n) - \alpha|^2)$$

2 Example

$$f = (x^2 + y^2 - 4, xy - 1)^T$$

$$\text{Jac}(f) = \begin{pmatrix} 2x & 2y \\ y & x \end{pmatrix}$$

Refer to p-0511.rr.