

Intersection theory for regular holonomic GKZ systems

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Introduction

We study GKZ hypergeometric systems (A -hypergeometric systems) from the view point of Euler-type integral representations of solutions. We can use the intersection theory of twisted homology and cohomology groups.

Contents

- ▶ Hypergeometric integrals and GKZ systems
- ▶ Cycles corresponding to series solutions (by Matsubara-Heo)
- ▶ Their intersection numbers
- ▶ Applications
 - ▶ Signature of monodromy invariant Hermitian forms
(Beukers-Verschoor's conjecture)
 - ▶ (Twisted period relations)

Gauss hypergeometric function

hypergeometric series

$${}_2F_1(a, b, c; z) = \sum_{n=0}^{\infty} \frac{(a)_n (b)_n}{(c)_n (1)_n} z^n,$$

$$(a)_n = a(a+1)\cdots(a+n-1) = \frac{\Gamma(a+n)}{\Gamma(a)}.$$

integral representation

$${}_2F_1(a, b, c; z) = \frac{\Gamma(c)}{\Gamma(a)\Gamma(c-a)} \int_0^1 x^{a-1} (1-x)^{c-a-1} (1-zx)^{-b} dx.$$

differential equation

We set $\theta_z = z \frac{d}{dz}$.

$$\left(\theta_z(\theta_z + c - 1) - z(\theta_z + a)(\theta_z + b) \right) \bullet {}_2F_1 = 0.$$

Hypergeometric integral

$$\int_0^1 x^{a-1} (1-x)^{c-a-1} (1-zx)^{-b} dx$$

(complex powers of polynomials (of degree 1))

↓ generalization

$$\int_{\Gamma} h_1(x)^{-\gamma_1} \dots h_k(x)^{-\gamma_k} \cdot x^c \frac{dx_1 \wedge \dots \wedge dx_d}{x_1 \dots x_d}$$

$$\left(\begin{array}{l} z^{(l)} = (z_1^{(l)}, \dots, z_{N_l}^{(l)}), \quad c = {}^t(c_1, \dots, c_d), \\ h_l(x) = h_l(z^{(l)}; x) = \sum_{j=1}^{N_l} z_j^{(l)} x^{\boldsymbol{a}^{(l)}(j)} \in \mathbb{C}[x_1^{\pm 1}, \dots, x_d^{\pm 1}], \\ \boldsymbol{a}^{(l)}(j) \in \mathbb{Z}^{d \times 1} \end{array} \right)$$

Example — ${}_2F_1$

$k = 2, d = 1, N_1 = N_2 = 2.$

$$\mathbf{a}^{(1)}(1) = 0, \quad \mathbf{a}^{(1)}(2) = 1, \quad \mathbf{a}^{(2)}(1) = 0, \quad \mathbf{a}^{(2)}(2) = 1.$$

We set $(z_1^{(1)}, z_2^{(1)} \mid z_1^{(2)}, z_2^{(2)}) = (z_1, z_2 \mid z_3, z_4).$

$$h_1(x) = h_1(z^{(1)}; x) = z_1^{(1)} \cdot x^{\mathbf{a}^{(1)}(1)} + z_2^{(1)} \cdot x^{\mathbf{a}^{(1)}(2)} = z_1 + z_2 x,$$

$$h_2(x) = h_2(z^{(2)}; x) = z_3 + z_4 x,$$

$$\begin{aligned} & \int_{\Gamma} (z_1 + z_2 x)^{-\gamma_1} (z_3 + z_4 x)^{-\gamma_2} x^c \frac{dx}{x} \quad \left(x = -\frac{z_1}{z_2} t \right) \\ &= (-1)^c z_1^{-\gamma_1+c} z_2^{-c} z_3^{-\gamma_2} \int_{\Gamma'} (1-t)^{-\gamma_1} \left(1 - \frac{z_1 z_4}{z_2 z_3} t \right)^{-\gamma_2} t^c \frac{dt}{t} \end{aligned}$$

This corresponds to the integral representation of
 ${}_2F_1\left(c, \gamma_2, 1 - \gamma_1 + c; \frac{z_1 z_4}{z_2 z_3}\right).$

Example — Appell's F_4

$k = 2, d = 2, N_1 = N_2 = 3.$

$$\mathbf{a}^{(1)}(1) = \begin{pmatrix} 0 \\ 0 \end{pmatrix}, \quad \mathbf{a}^{(1)}(2) = \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \quad \mathbf{a}^{(1)}(3) = \begin{pmatrix} 0 \\ 1 \end{pmatrix},$$

$$\mathbf{a}^{(2)}(1) = \begin{pmatrix} 0 \\ 0 \end{pmatrix}, \quad \mathbf{a}^{(2)}(2) = \begin{pmatrix} -1 \\ 0 \end{pmatrix}, \quad \mathbf{a}^{(2)}(3) = \begin{pmatrix} 0 \\ -1 \end{pmatrix}.$$

We set $(z_1^{(1)}, z_2^{(1)}, z_3^{(1)} \mid z_1^{(2)}, z_2^{(2)}, z_3^{(2)}) = (z_1, z_2, z_3 \mid z_4, z_5, z_6).$

$$h_1(x) = z_1 \cdot x^{\binom{0}{0}} + z_2 \cdot x^{\binom{1}{0}} + z_3 \cdot x^{\binom{0}{1}} = z_1 + z_2 x_1 + z_3 x_2,$$

$$h_2(x) = z_4 \cdot x^{\binom{0}{0}} + z_5 \cdot x^{\binom{-1}{0}} + z_6 \cdot x^{\binom{0}{-1}} = z_4 + \frac{z_5}{x_1} + \frac{z_6}{x_2}.$$

$$\rightsquigarrow \int_{\Gamma} (z_1 + z_2 x_1 + z_3 x_2)^{-\gamma_1} \left(z_4 + \frac{z_5}{x_1} + \frac{z_6}{x_2} \right)^{-\gamma_2} x_1^{c_1} x_2^{c_2} \frac{dx_1 \wedge dx_2}{x_1 x_2}$$

For a “cycle” Γ ,

$$\int_{\Gamma} h_1(z^{(1)}; x)^{-\gamma_1} \cdots h_k(z^{(k)}; x)^{-\gamma_k} \cdot x^c \frac{dx_1 \wedge \cdots \wedge dx_d}{x_1 \cdots x_d}$$

is a solution to the GKZ system $M_A(\delta)$
(w.r.t. variables $z = (z^{(1)} | z^{(2)} | \cdots | z^{(k)})$), where

$$A = \left(\begin{array}{ccc|ccc|c|ccc} 1 & \cdots & 1 & 0 & \cdots & 0 & & 0 & \cdots & 0 \\ 0 & \cdots & 0 & 1 & \cdots & 1 & & 0 & \cdots & 0 \\ \hline & & & & & & \ddots & & & \\ \hline 0 & \cdots & 0 & 0 & \cdots & 0 & & 1 & \cdots & 1 \\ \hline A_1 & & & A_2 & & & \cdots & & A_k \end{array} \right)$$

$$(A_l = (\mathbf{a}^{(l)}(1), \dots, \mathbf{a}^{(l)}(N_l)) \in \mathbb{Z}^{d \times N_l})$$

$$\delta = {}^t(\gamma_1, \dots, \gamma_k, c_1, \dots, c_d) \in \mathbb{C}^{(k+d) \times 1} : \text{generic.}$$

GKZ hypergeometric system (A -hypergeometric system)

$A \in \mathbb{Z}^{n \times N}$ & $\delta \in \mathbb{C}^{n \times 1} \rightsquigarrow$ GKZ system $M_A(\delta)$
(a system of differential equations)

Fact ([Hotta, 1998])

For our A , $M_A(\delta)$ is regular holonomic.

$\Delta_A = (\text{the convex hull of the column vectors of } A) \subset \mathbb{R}^n$,

$\text{Vol}(A) = (\text{the normalized volume of } \Delta_A) \in \mathbb{N}$

Fact ([GZK, 1989])

If δ is “generic”, then $\text{rank}(M_A(\delta)) = \text{Vol}(A)$.

For a generic $z \in \mathbb{C}^N$, $Sol_{M_A(\delta), z}$ denotes the space of the local solutions around z . We have $\dim Sol_{M_A(\delta), z} = \text{Vol}(A)$.

Example — ${}_2F_1$

$$\mathbf{a}^{(1)}(1) = 0, \quad \mathbf{a}^{(1)}(2) = 1 \longrightarrow A_1 = (0 \ 1)$$

$$\mathbf{a}^{(2)}(1) = 0, \quad \mathbf{a}^{(2)}(2) = 1 \longrightarrow A_2 = (0 \ 1)$$

$$A = \left(\begin{array}{cc|cc} 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ \hline 0 & 1 & 0 & 1 \end{array} \right) \quad \left(\begin{array}{l} k = 2, \ d = 1, \ n = k + d = 3 \\ A_1 = A_2 = (\mathbf{0} \ \mathbf{1}), \\ (z_1^{(1)}, z_2^{(1)} \mid z_1^{(2)}, z_2^{(2)}) = (z_1, z_2 \mid z_3, z_4) \end{array} \right)$$
$$\delta = {}^t(\gamma_1, \gamma_2, c)$$

$\int_{\Gamma} (z_1 + z_2 x)^{-\gamma_1} (z_3 + z_4 x)^{-\gamma_2} \ x^c \ \frac{dx}{x}$ is a solution to $M_A(\delta)$.

$$\text{Vol}(A) = 2.$$

(formal) power series solutions

If $v = \begin{pmatrix} v_1 \\ \vdots \\ v_N \end{pmatrix} \in \mathbb{C}^{N \times 1}$ satisfies $Av = -\delta$, then the series

$$\varphi_v(z) = z^v \sum_{u \in \text{Ker}_{\mathbb{Z}A}} \frac{1}{\Gamma(u + v + 1)} z^u$$

$$\left(z^v = z_1^{v_1} \cdots z_N^{v_N}, \quad \Gamma(u + v + 1) = \prod_{j=1}^N \Gamma(u_j + v_j + 1) \right)$$

is a (formal) solution to $M_A(\delta)$.

Fact ([GZK, 1989])

T : a regular triangulation of Δ_A

\rightsquigarrow We can take $v_1, \dots, v_r \in \mathbb{C}^{N \times 1}$ ($r = \text{Vol}(A)$) such that $\{\varphi_{v_i}\}_{i=1}^r$ form a basis of $Sol_{M_A(\delta), z}$.

Example — ${}_2F_1$

$\{(123), (234)\} \cdots$ a regular triangulation of Δ_A

$$A = \left(\begin{array}{cc|cc} 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ \hline 0 & 1 & 0 & 1 \end{array} \right) \quad \delta = \begin{pmatrix} \gamma_1 \\ \gamma_2 \\ c \end{pmatrix} =: \begin{pmatrix} \delta_1 \\ \delta_2 \\ \delta_3 \end{pmatrix}$$

$$v = \begin{pmatrix} -\delta_1 + \delta_3 \\ -\delta_3 \\ -\delta_2 \\ 0 \end{pmatrix} (\leftrightarrow (123)), \quad v' = \begin{pmatrix} 0 \\ -\delta_1 \\ -\delta_1 - \delta_2 + \delta_3 \\ \delta_1 - \delta_3 \end{pmatrix} (\leftrightarrow (234))$$

satisfy $Av = Av' = -\delta$.

$$\varphi_v = \frac{z_1^{-\delta_1+\delta_3} z_2^{-\delta_3} z_3^{-\delta_2} \cdot {}_2F_1\left(\delta_3, \delta_2, 1 - \delta_1 + \delta_3; \frac{z_1 z_4}{z_2 z_3}\right)}{\Gamma(1 - \delta_3) \Gamma(1 - \delta_2) \Gamma(1 - \delta_1 + \delta_3)},$$

$$\varphi_{v'} = \frac{z_1^{-\delta_1+\delta_3} z_2^{-\delta_3} z_3^{-\delta_2} \cdot \left(\frac{z_1 z_4}{z_2 z_3}\right)^{\delta_1-\delta_3} {}_2F_1\left(\delta_1, \delta_1 + \delta_2 - \delta_3, 1 + \delta_1 - \delta_3; \frac{z_1 z_4}{z_2 z_3}\right)}{\Gamma(1 - \delta_1) \Gamma(1 - \delta_1 - \delta_2 + \delta_3) \Gamma(1 + \delta_1 - \delta_3)}$$

$\varphi_v, \varphi_{v'}$ correspond to “well-known” solutions around $\frac{z_1 z_4}{z_2 z_3} = 0$.

Twisted (co)homology group

$$\int_{\Gamma} h_1(x)^{-\gamma_1} \cdots h_k(x)^{-\gamma_k} \cdot x^c \frac{dx}{x} \quad \left(\frac{dx}{x} = \frac{dx_1 \wedge \cdots \wedge dx_d}{x_1 \cdots x_d} \right)$$

The “cycle” Γ (twisted cycle) can be regarded as an element of
twisted homology group $H_d(X; \Phi)$

$$\begin{aligned} &\equiv \{ (\text{domain of integration} \subset X (\leftarrow x\text{-space})) \\ &\quad \& (\text{the branch of multi-val. func. } \Phi(x) = \prod_{l=1}^k h_l(x)^{-\gamma_l} \cdot x^c) \}. \end{aligned}$$

It is dual to

twisted cohomology group $H^d(X; \nabla)$

$$= (\text{de-Rham cohomology w.r.t. } \nabla = d + d \log \Phi \wedge \quad (d = d_x)).$$

The pairing between them gives hypergeometric integrals.

Fact ([GKZ, 1990])

$$H_d(X; \Phi) \xrightarrow{\sim} Sol_{M_A(\delta), z}; \quad \Gamma \longmapsto \int_{\Gamma} \Phi \frac{dx}{x}$$

Because of $H_d(X; \Phi) \xrightarrow{\sim} Sol_{M_A(\delta), z}$, there exists a cycle such that

$$\varphi_v(z) = \int_{\Gamma} \Phi \frac{dx}{x} = \int_{\Gamma} \prod_{l=1}^k h_l(z^{(l)}; x)^{-\gamma_l} \cdot x^c \frac{dx}{x}.$$

(power series sol.)

→ How to construct such cycles?

Fact ([Matsubara-Heo; arXiv:1904.00565])

T : a regular triangulation of $\Delta_A \rightsquigarrow \{\varphi_{v_i}\}_{i=1}^r$: a basis of $Sol_{M_A(\delta), z}$

⇒ We can construct cycles $\{\Gamma_i\}_{i=1}^r$ such that

$$\int_{\Gamma_i} \prod_{l=1}^k h_l(z^{(l)}; x)^{-\gamma_l} \cdot x^c \frac{dx}{x} = \varphi_{v_i}(z).$$

An explicit construction is given.

Intersection forms

By replacing Φ with $\Phi^{-1} = 1/\Phi$, we consider
the twisted homology $H_d(X; \Phi^{-1})$ and
the twisted cohomology $H^d(X; \nabla^-)$ ($\nabla^- = d - d \log \Phi \wedge$).

Intersection form ([Kita-Yoshida, 1994], [Cho-Matsumoto, 1995])

- ▶ **homology** $I_h: H_d(X; \Phi) \times H_d(X; \Phi^{-1}) \rightarrow \mathbb{C}$
..... topological int. num. + information of branches.
- ▶ **cohomology** $I_c: H^d(X; \nabla) \times H^d(X; \nabla^-) \rightarrow \mathbb{C}$
..... taking the exterior product & integrating it on X .

Theorem 1 ([G.-Matsubara-Heo; 2022, Theorem 2.6])

The intersection matrix $(I_h(\Gamma_i, \Gamma_j))_{i,j=1,\dots,r}$ is explicitly evaluated.

Applications

- ▶ Signatures of invariant Hermitian forms
(Beukers-Verschoor's conjecture)
- ▶ Twisted period relations (quadratic relations of HG series)

Monodromy, Invariant Hermitian form

By considering the analytic continuation of the solutions, we have the monodromy representation

$$\begin{aligned}\pi_1(\mathbb{C}^N - (\text{singular locus}), z) &\rightarrow GL(Sol_{M_A(\delta), z}) \\ \rho &\mapsto \rho_* \text{ (: analytic conti. along } \rho\text{).}\end{aligned}$$

For $\delta \in \mathbb{R}^{n \times 1}$, there exist a monodromy invariant Hermitian form (unique up to constant):

$$\begin{aligned}(\bullet, \bullet) : Sol_{M_A(\delta), z} \times Sol_{M_A(\delta), z} &\rightarrow \mathbb{C}, \\ (\rho_* f, \rho_* g) &= (f, g) \quad (\forall \rho \in \pi_1).\end{aligned}$$

We consider its signature.

Beukers-Verschoor's conjecture

T : a regular triangulation of Δ_A ,

$\rightsquigarrow \{\varphi_{v_i}\}_{i=1}^r$: a basis of $Sol_{M_A(\delta), z}$

$(v_i = {}^t(v_{i1}, \dots, v_{iN}) \in \mathbb{R}^{N \times 1} \leftrightarrow \sigma \in T (\sigma \subset \{1, \dots, N\}))$

Beukers-Verschoor's conjecture (cf. [Verschoor; 2022])

The signature of the monodromy invariant Hermitian form is given by

$$\left\{ \operatorname{sgn} \left(\prod_{j \in \sigma} \sin \pi v_{ij} \right) \right\}_{i=1, \dots, r}$$

Example — ${}_2F_1$

$$A = \begin{pmatrix} 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 1 & 0 & 1 \end{pmatrix}$$
$$v = \begin{pmatrix} -\delta_1 + \delta_3 \\ -\delta_3 \\ -\delta_2 \\ 0 \end{pmatrix} \quad (\leftrightarrow (123) \in T)$$
$$\Rightarrow Av = Av' = \begin{pmatrix} -\delta_1 \\ -\delta_2 \\ -\delta_3 \end{pmatrix}.$$
$$v' = \begin{pmatrix} 0 \\ -\delta_1 \\ -\delta_1 - \delta_2 + \delta_3 \\ \delta_1 - \delta_3 \end{pmatrix} \quad (\leftrightarrow (234) \in T)$$

We set

$$\alpha := \sin \pi(-\delta_1 + \delta_3) \cdot \sin \pi(-\delta_3) \cdot \sin \pi(-\delta_2),$$

$$\alpha' := \sin \pi(-\delta_1) \cdot \sin \pi(-\delta_1 - \delta_2 + \delta_3) \cdot \sin \pi(\delta_1 - \delta_3).$$

Then the signature is given by $(\text{sgn}(\alpha), \text{sgn}(\alpha'))$.

Theorem 2 ([G.-Matsubara-Heo; 2022, Theorem 2.12])

The signature of the monodromy invariant Hermitian form is given by

$$\left\{ \operatorname{sgn} \left(\prod_{j \in \sigma} \sin \pi v_{ij} \right) \right\}_{i=1,\dots,r}$$

Proof.

$$H_d(X; \Phi) \xrightarrow{\sim} \text{Sol}_{M_A(\delta), z}$$

(intersection form) \longleftrightarrow (inv. Herm. form)

We can compute the eigenvalues of the intersection matrix in Theorem 1. □

Twisted period relations

Proposition

$\{\Gamma_j^\pm\}_{j=1}^r$: bases of $H_d(X; \Phi^{\pm 1})$

$\{\psi_i^\pm\}_{i=1}^r$: bases of $H^d(X; \nabla^\pm)$

$$H = \left(I_h(\Gamma_i^+, \Gamma_j^-) \right)_{i,j=1,\dots,r}, \quad C = \left(I_c(\psi_i^+, \psi_j^-) \right)_{i,j=1,\dots,r},$$

$$\Pi_+ = \left(\int_{\Gamma_j^+} \Phi \psi_i^+ \right)_{i,j=1,\dots,r}, \quad \Pi_- = \left(\int_{\Gamma_j^-} \Phi^{-1} \psi_i^- \right)_{i,j=1,2}.$$

We have

$$C = \Pi_+ {}^t H^{-1} {}^t \Pi_-.$$

cohomology intersection number = sum of product of HG series

By Theorem 1, we obtain an explicit form of RHS.

- ▶ A hypergeometric integral (an integral of the product of complex powers of Laurent polynomials) is a solution to a GKZ system.
- ▶ Matsubara-Heo constructed cycles (domains of integration) which correspond to series solutions to the GKZ system.
- ▶ We evaluate their intersection numbers.
- ▶ By using our intersection matrix, we can prove Beukers-Verschoor's conjecture.

Thank you for your kind attention!

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