

The variant of the q -hypergeometric equation of degree three: a q -analog of Papperitz's differential system

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Two variants of the q -hypergeometric equation \mathcal{H}_2 and \mathcal{H}_3 are introduced by Hatano-Matsunawa-Sato-Takemura from the viewpoint of some quantum integrable system.

In this talk, we will discuss \mathcal{H}_3 mainly.

We will show that this equation can be regarded as a q -analog of the Riemann-Papperitz differential system.

From this aspect, we will give integral solutions and series solutions for the equation \mathcal{H}_3 .

If time permits, we will show some applications.

§1 Introduction pp.3–8.

§2 Solutions for the equation \mathcal{H}_3 pp.9–25.

§3 Some applications (if time permits) pp.26–36.

Notations

Throughout this talk, we fix $q \in \mathbb{C}$ with $0 < |q| < 1$.

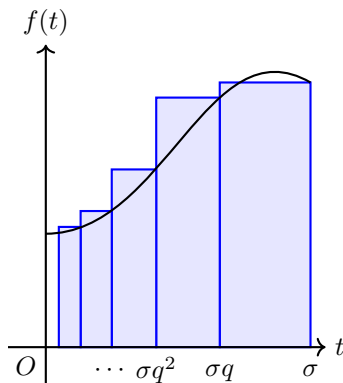
the q -shifted factorial (the q -Pochhammer symbol):

$$(a)_\infty = \prod_{i=0}^{\infty} (1 - aq^i), \quad (a)_n = \frac{(a)_\infty}{(aq^n)_\infty}, \quad (a_1, \dots, a_M)_n = (a_1)_n \cdots (a_M)_n.$$

the Jackson integral:

$$\int_0^\sigma f(t) d_q t = (1 - q)\sigma \sum_{i=0}^{\infty} f(\sigma q^i) q^i,$$
$$\int_0^{\sigma\infty} f(t) d_q t = (1 - q)\sigma \sum_{i=-\infty}^{\infty} f(\sigma q^i) q^i,$$
$$\int_{\sigma_1}^{\sigma_2} f(t) d_q t = \int_0^{\sigma_2} f(t) d_q t - \int_0^{\sigma_1} f(t) d_q t.$$

the q -shift operator: $T_x f(x) = f(qx)$.



Main result

The variant of the q -hypergeometric equation of degree three is defined as follows:

$$\begin{aligned}\mathcal{H}_3 y &= 0, \\ \mathcal{H}_3 &= \prod_{i=1}^3 (x - q^{h_i+1/2} t_i) \cdot T_x^{-1} + q^{2\alpha+1} \prod_{i=1}^3 (x - q^{l_i-1/2} t_i) \cdot T_x \\ &\quad - q^\alpha \left[(q+1)x^3 - q^{1/2} \sum_{i=1}^3 (q^{h_i} + q^{l_i}) t_i x^2 \right. \\ &\quad \left. + q^{(h_1+h_2+h_3+l_1+l_2+l_3+1)/2} t_1 t_2 t_3 \sum_{i=1}^3 \frac{q^{-h_i} + q^{-l_i}}{t_i} x \right. \\ &\quad \left. - q^{(h_1+h_2+h_3+l_1+l_2+l_3)/2} (q+1) t_1 t_2 t_3 \right].\end{aligned}$$

The functions

$$x^{\nu-\alpha} \int_{\sigma_1}^{\sigma_2} \frac{(q^\nu xt, q^{h_1+\frac{1}{2}}t_1t, q^{h_2+\frac{1}{2}}t_2t, q^{h_3+\frac{1}{2}}t_3t)_\infty}{(xt, q^{\nu+l_1-\frac{1}{2}}t_1t, q^{\nu+l_2-\frac{1}{2}}t_2t, q^{\nu+l_3-\frac{1}{2}}t_3t)_\infty} d_q t,$$

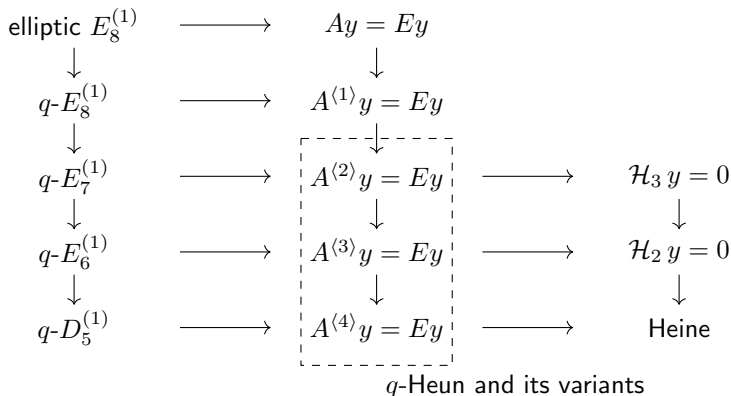
$$x^{\nu-\alpha} \frac{(q^{\nu-h_3+\frac{1}{2}}x/t_3)_\infty}{(q^{\frac{1}{2}-h_3}x/t_3)_\infty}$$

$$\times {}_8W_7 \left(\frac{t_1q^{h_1-h_3+\nu}}{t_3}; \frac{t_1q^{-h_3+l_1+\nu}}{t_3}, \frac{t_2q^{-h_3+l_2+\nu}}{t_3}, q^{-h_3+l_3+\nu}, \frac{t_1q^{h_1+\frac{1}{2}}}{x}, q^\nu; \frac{xq^{\frac{1}{2}-h_2}}{t_2} \right),$$

satisfy $\mathcal{H}_3 y = 0$, where $\nu = \frac{1}{2}(h_1 + h_2 + h_3 - l_1 - l_2 - l_3 + 1)$,
 $\sigma_1, \sigma_2 \in \{q^{\frac{1}{2}-h_1}/t_1, q^{\frac{1}{2}-h_2}/t_2, q^{\frac{1}{2}-h_3}/t_3, q^{1-\nu}/x\}$ and

$${}_8W_7(a; b, c, d, e, f; z) = \sum_{n=0}^{\infty} \frac{1 - aq^{2n}}{1 - a} \frac{(a, b, c, d, e, f)_n}{(q, qa/b, qa/c, qa/d, qa/e, qa/f)_n} z^n.$$

Background



A brief review for the Heine's equation

The Heine's q -hypergeometric equation is defined as follows:

$$[(1 - T_x)(1 - cq^{-1}T_x) - x(1 - aT_x)(1 - bT_x)]y = 0.$$

This equation is a q -analog of the Gauss hypergeometric equation. More precisely, by taking the classical limit $q \rightarrow 1$ with $a = q^\alpha$, $b = q^\beta$, $c = q^\gamma$, we get

$$\left[x(1-x) \frac{d^2}{dx^2} + (\gamma - (\alpha + \beta + 1)x) \frac{d}{dx} - \alpha\beta \right] y = 0.$$

The variants of the q -hypergeometric equation \mathcal{H}_2 and \mathcal{H}_3 are some extensions for the Heine's equation.

The Gauss equation has Euler type integral solutions and series solutions in terms of the Gauss hypergeometric function ${}_2F_1$:

$$\int_C t^{\alpha-1}(1-t)^{\gamma-\alpha-1}(1-xt)^{-\beta} dt,$$

$${}_2F_1 \left(\begin{matrix} \alpha, \beta \\ \gamma \end{matrix} ; x \right) = 1 + \frac{\alpha \cdot \beta}{\gamma \cdot 1} x + \frac{\alpha(\alpha+1) \cdot \beta(\beta+1)}{\gamma(\gamma+1) \cdot 1 \cdot 2} x^2 + \dots$$

Similarly the Heine's equation has solutions in terms of q -analogs of the above functions:

$$\int_C t^{\alpha-1} \frac{(qt)_{\infty}}{(ct/a)_{\infty}} \frac{(bxt)_{\infty}}{(xt)_{\infty}} d_q t \quad (q^{\alpha} = a), \quad \left(\frac{(q^{\alpha}x)_{\infty}}{(x)_{\infty}} \xrightarrow{q \rightarrow 1} (1-x)^{-\alpha} \right)$$

$${}_2\varphi_1 \left(\begin{matrix} a, b \\ c \end{matrix} ; x \right) = \sum_{n=0}^{\infty} \frac{(a)_n (b)_n}{(c)_n (q)_n} x^n$$

$$= 1 + \frac{(1-a)(1-b)}{(1-c)(1-q)} x + \frac{(1-a)(1-aq)(1-b)(1-bq)}{(1-c)(1-cq)(1-q)(1-q^2)} x^2 + \dots$$

The equation $\mathcal{H}_3 y = 0$ (recall)

The variant of the q -hypergeometric equation of degree three is defined as follows:

$$\begin{aligned} \mathcal{H}_3 y &= 0, \\ \mathcal{H}_3 &= \prod_{i=1}^3 (x - q^{h_i+1/2} t_i) \cdot T_x^{-1} + q^{2\alpha+1} \prod_{i=1}^3 (x - q^{l_i-1/2} t_i) \cdot T_x \\ &\quad - q^\alpha \left[(q+1)x^3 - q^{1/2} \sum_{i=1}^3 (q^{h_i} + q^{l_i}) t_i x^2 \right. \\ &\quad \left. + q^{(h_1+h_2+h_3+l_1+l_2+l_3+1)/2} t_1 t_2 t_3 \sum_{i=1}^3 \frac{q^{-h_i} + q^{-l_i}}{t_i} x \right. \\ &\quad \left. - q^{(h_1+h_2+h_3+l_1+l_2+l_3)/2} (q+1) t_1 t_2 t_3 \right]. \end{aligned}$$

Characterization

Suppose an operator $H = \sum_{i=0}^3 \sum_{j=-1}^1 a_{i,j} x^i T_x^j$ satisfies the following conditions:

- We rewrite $H = \sum_{i=0}^3 x^i L_i(T_x)$, then
 - $L_0(y) \propto (y - a)(y - aq)$, $L_1(y) \propto (y - a)$.
 - $L_3(y) \propto (y - b)(y - bq^{-1})$, $L_2(y) \propto (y - b)$.
- We rewrite $H = \sum_{j=-1}^1 P_j(x) T_x^j$, then
 - $P_{-1}(x) \propto (x - c_1)(x - c_2)(x - c_3)$.
 - $P_1(x) \propto (x - d_1)(x - d_2)(x - d_3)$.

Then the equation $Hy = 0$ is equivalent to the equation $\mathcal{H}_3 y = 0$.

Classical limit $q \rightarrow 1$

By taking the limit $q \rightarrow 1$, the equation $\mathcal{H}_3 y = 0$ becomes a Fuchsian differential equation which has the following Riemann scheme:

$$\left\{ \begin{array}{ccccc} x = 0 & t_1 & t_2 & t_3 & \infty \\ \rho_0 & 0 & 0 & 0 & \rho_\infty \\ \rho_0 + 1 & * & * & * & \rho_\infty + 1 \end{array} \right\}.$$

The points $x = 0$ and ∞ are essentially non-singular (i.e. these points can be transformed to regular points by some gauge factor).

By some gauge transformation, this differential equation is transformed to

$$\left\{ \begin{array}{ccc} x = t_1 & t_2 & t_3 \\ * & * & * \\ * & * & * \end{array} \right\}.$$

This equation is called the Riemann-Papperitz's differential equation.

Solutions for the Riemann-Papperitz's equation

The Riemann-Papperitz's differential equation can be transformed to the Gauss' hypergeometric equation by the Möbius transformation

$$x \mapsto \frac{x - t_1}{x - t_3} \frac{t_2 - t_3}{t_2 - t_1}.$$

It is well known that the Gauss' equation has Euler-type integral solutions and series solutions in terms of the hypergeometric function ${}_2F_1$:

$$\int_C t^{\alpha-1} (1-t)^{\gamma-\alpha-1} (1-xt)^{-\beta} dt, \quad {}_2F_1 \left(\begin{matrix} \alpha, \beta \\ \gamma \end{matrix} ; x \right).$$

So we get solutions for the Riemann-Papperitz's equation:

$$(\text{gauge factor}) \times \int_C (t-x)^{\nu_0} (t-t_1)^{\nu_1} (t-t_2)^{\nu_2} (t-t_3)^{\nu_3} dt,$$

$$(\text{gauge factor}) \times {}_2F_1 \left(\begin{matrix} \mu_1, \mu_2 \\ \mu_3 \end{matrix} ; \frac{x-t_1}{x-t_3} \frac{t_2-t_3}{t_2-t_1} \right),$$

where $\nu_0 + \nu_1 + \nu_2 + \nu_3 = -2$.

Observation

- The equation $\mathcal{H}_3 y = 0$ can be regarded as a q -analog of the Riemann-Papperitz's differential system.
- The Riemann-Papperitz's system has integral solutions and series solutions as follows:

$$(\text{gauge factor}) \times \int_C (t-x)^{\nu_0} (t-t_1)^{\nu_1} (t-t_2)^{\nu_2} (t-t_3)^{\nu_3} dt,$$

$$(\text{gauge factor}) \times {}_2F_1 \left(\begin{matrix} \mu_1, \mu_2 \\ \mu_3 \end{matrix} ; \frac{x-t_1}{x-t_3} \frac{t_2-t_3}{t_2-t_1} \right),$$

where $\nu_0 + \nu_1 + \nu_2 + \nu_3 = -2$.

\rightsquigarrow Naively it is expected that the equation $\mathcal{H}_3 y = 0$ has solutions in terms of q -analogs of these functions.

We consider q -analogs of such solutions for the Riemann-Papperitz's system.

- It is difficult to directly consider a q -analog of the series

$${}_2F_1 \left(\begin{matrix} \mu_1, \mu_2 \\ \mu_3 \end{matrix} ; \frac{x - t_1}{x - t_3} \frac{t_2 - t_3}{t_2 - t_1} \right).$$

In the theory of q -difference equations, the points $x = 0$ and ∞ are special points because these are fixed points of the q -shift operator $T_x : x \mapsto qx \mapsto q^2x \mapsto \dots$. So we cannot apply some Möbius transformation to q -difference equations.

- It is easy to consider a q -analog of the integral

$$\int_C (t - x)^{\nu_0} (t - t_1)^{\nu_1} (t - t_2)^{\nu_2} (t - t_3)^{\nu_3} dt,$$

by the q -binomial theorem $\left(\frac{(q^\alpha x)_\infty}{(x)_\infty} \xrightarrow{q \rightarrow 1} (1 - x)^{-\alpha} \right)$.

In short, we should consider the following Jackson integral:

$$\int_C \frac{(q^{-\nu_0}xt)_\infty}{(xt)_\infty} \frac{(q^{-\nu_1}t_1t)_\infty}{(t_1t)_\infty} \frac{(q^{-\nu_2}t_2t)_\infty}{(t_2t)_\infty} \frac{(q^{-\nu_3}t_3t)_\infty}{(t_3t)_\infty} d_q t,$$

where $\nu_0 + \nu_1 + \nu_2 + \nu_3 = -2$. This integral is equivalent to

$$\int_C \frac{(Axt)_\infty}{(Bxt)_\infty} \prod_{i=1}^3 \frac{(a_i t)_\infty}{(b_i t)_\infty} d_q t,$$

where $Aa_1a_2a_3 = q^2Bb_1b_2b_3$.

We will derive a q -difference equation that the integral satisfies.

To derive it, a q -difference equation that the integrand satisfies will be considered.

$$\psi = \psi(x, t) = \frac{(Axt)_\infty}{(Bxt)_\infty} \prod_{i=1}^3 \frac{(a_i t)_\infty}{(b_i t)_\infty}.$$

The integrand $\psi = \frac{(Axt)_\infty}{(Bxt)_\infty} \prod_{i=1}^3 \frac{(a_it)_\infty}{(b_it)_\infty}$ satisfies the following system:

$$T_x \psi = \frac{1 - Bxt}{1 - Axt} \psi, \quad T_x^{-1} T_t \psi = \prod_{i=1}^3 \frac{1 - b_it}{1 - a_it} \psi.$$

So we get the equations:

$$tx(B - AT_x)\psi = (1 - T_x)\psi,$$

$$\sum_{k=0}^3 (-1)^k t^k (e_k(a)T_x^{-1}T_t - e_k(b)) \psi = 0.$$

Here e_k is the k -th elementary symmetric function.

By using the first equation, we can delete t^k from the second equation.

We get the following:

$$\begin{aligned}
 & [x^3(B - Aq^2T_x)(B - AqT_x)(B - AT_x)(T_x^{-1}T_t - 1) \\
 & - x^2(B - AqT_x)(B - AT_x)(e_1(a)T_x^{-1}T_t - e_1(b))(1 - T_x) \\
 & + x(B - AT_x)(e_2(a)T_x^{-1}T_t - e_2(b))(1 - q^{-1}T_x)(1 - T_x) \\
 & - (e_3(a)T_x^{-1}T_t - e_3(b))(1 - q^{-2}T_x)(1 - q^{-1}T_x)(1 - T_x)]\psi = 0.
 \end{aligned}$$

By integrating this equation with t , we can delete T_t because

$$\int_0^{\sigma\infty} T_t f(t) d_q t = q^{-1} \int_0^{\sigma\infty} f(t) d_q t.$$

So we obtain a linear q -difference equation of rank 4 that the integral

$$\varphi = \varphi(x, \sigma) = \int_0^{\sigma\infty} \psi(x, t) d_q t \text{ satisfies.}$$

We find

$$\begin{aligned}
 & [x^3(B - Aq^2T_x)(B - AqT_x)(B - AT_x)(T_x^{-1}q^{-1} - 1) \\
 & - x^2(B - AqT_x)(B - AT_x)(e_1(a)T_x^{-1}q^{-1} - e_1(b))(1 - T_x) \\
 & + x(B - AT_x)(e_2(a)T_x^{-1}q^{-1} - e_2(b))(1 - q^{-1}T_x)(1 - T_x) \\
 & - (e_3(a)T_x^{-1}q^{-1} - e_3(b))(1 - q^{-2}T_x)(1 - q^{-1}T_x)(1 - T_x)]\varphi(x, \sigma) = 0.
 \end{aligned}$$

This equation is reducible:

$$\begin{aligned}
 & (B - Aq^{-1}T_x)(1 - q^{-2}T_x)H_3\varphi(x, \sigma) = 0, \\
 & H_3 = x^3(B - AqT_x)(B - AT_x)T_x^{-1} - x^2(B - AT_x)(e_1(a)T_x^{-1} - qe_1(b)) \\
 & + x(e_2(a)T_x^{-1} - qe_2(b))(1 - T_x) - \frac{a_1a_2a_3}{B}(1 - q^{-1}T_x)(1 - T_x)T_x^{-1}.
 \end{aligned}$$

The equation $H_3 y = 0$ is equivalent to the variant of the q -hypergeometric equation of degree three $\mathcal{H}_3 y = 0$.

More precisely, we put $A = q^\nu$, $B = 1$, $a_i = t_i q^{h_i + \frac{1}{2}}$, $b_i = t_i q^{l_i - \frac{1}{2} + \nu}$ and apply some gauge transformation $y \rightarrow x^{\nu - \alpha} y$, then $H_3 y = 0$ becomes $\mathcal{H}_3 y = 0$.

Now we have $(B - Aq^{-1}T_x)(1 - q^{-2}T_x)H_3\varphi(x, \sigma) = 0$.

So we want to delete the terms $(B - Aq^{-1}T_x)(1 - q^{-2}T_x)$.

- $(B - Aq^{-1}T_x)y = 0 \rightsquigarrow y = Cx^\lambda$, ($q^\lambda = Bq/A$).

- $(1 - q^{-2}T_x)y = 0 \rightsquigarrow y = Cx^2$.

\rightsquigarrow We get $H_3\varphi(x, \sigma) = C_1x^\lambda + C_2x^2$.

By some calculations, we find the following:

$$H_3\varphi(x, \sigma) = (A - B)qx^2, \quad (\sigma \in \{q/a_1, q/a_2, q/a_3, q/(Ax)\}).$$

Integral solutions

Finally we get 6 integral solutions for the equation $H_3 y = 0$:

$$\int_{\sigma_1}^{\sigma_2} \frac{(Axt)_\infty}{(Bxt)_\infty} \prod_{i=1}^3 \frac{(a_i t)_\infty}{(b_i t)_\infty} d_q t,$$

where $Aa_1a_2a_3 = q^2Bb_1b_2b_3$ and $\sigma_1, \sigma_2 \in \{q/a_1, q/a_2, q/a_3, q/(Ax)\}$.
These are q -analogs of integral solutions

$$\int_C (t-x)^{\nu_0} (t-t_1)^{\nu_1} (t-t_2)^{\nu_2} (t-t_3)^{\nu_3} dt,$$

for the Riemann-Papperitz's equation.

From integral solutions to series solutions

Next, we give series solutions for the equation $H_3 y = 0$.

By the Bailey's formula

$$\begin{aligned} & \int_a^b \frac{(qt/a, qt/b, ct, dt)_\infty}{(et, ft, gt, ht)_\infty} d_q t \\ &= b(1-q) \frac{(q, bq/a, a/b, cd/eh, cd/fh, cd/gh, bc, bd)_\infty}{(ae, af, ag, be, bf, bg, bh, bcd/h)_\infty} \\ & \times {}_8W_7(bcd/hq; be, bf, bg, c/h, d/h; ah) \quad (cd = abefgh), \end{aligned}$$

we get solutions for the equation $H_3 y = 0$ in terms of the very-well-poised q -hypergeometric function ${}_8W_7$. Here,

$${}_8W_7(a; b, c, d, e, f; z) = \sum_{n=0}^{\infty} \frac{1 - aq^{2n}}{1 - a} \frac{(a, b, c, d, e, f)_n}{(q, qa/b, qa/c, qa/d, qa/e, qa/f)_n} z^n.$$

Applying the Bailey's formula, we have

$$\int_{q/a_1}^{q/a_3} \frac{(Axt, a_1t, a_2t, a_3t)_\infty}{(Bxt, b_1t, b_2t, b_3t)_\infty} d_q t$$

$$= (\text{const.}) \frac{(Axq/a_3)_\infty}{(Bxq/a_3)_\infty} {}_8W_7 \left(\frac{a_2A}{a_3B}; \frac{qb_1}{a_3}, \frac{qb_2}{a_3}, \frac{qb_3}{a_3}, \frac{a_2}{Bx}, \frac{A}{B}; \frac{Bxq}{a_1} \right).$$

Therefore the function

$$\frac{(Axq/a_3)_\infty}{(Bxq/a_3)_\infty} {}_8W_7 \left(\frac{a_2A}{a_3B}; \frac{qb_1}{a_3}, \frac{qb_2}{a_3}, \frac{qb_3}{a_3}, \frac{a_2}{Bx}, \frac{A}{B}; \frac{Bxq}{a_1} \right),$$

satisfies the equation $H_3 y = 0$.

Solutions for $\mathcal{H}_3 y = 0$

We get integral solutions and series solutions for $H_3 y = 0$.

So we have solutions for the original equation $\mathcal{H}_3 y = 0$:

$$x^{\nu-\alpha} \int_{\sigma_1}^{\sigma_2} \frac{(q^\nu xt, q^{h_1+\frac{1}{2}}t_1t, q^{h_2+\frac{1}{2}}t_2t, q^{h_3+\frac{1}{2}}t_3t)_\infty}{(xt, q^{\nu+l_1-\frac{1}{2}}t_1t, q^{\nu+l_2-\frac{1}{2}}t_2t, q^{\nu+l_3-\frac{1}{2}}t_3t)_\infty} d_q t,$$

$$x^{\nu-\alpha} \frac{(q^{\nu-h_3+\frac{1}{2}}x/t_3)_\infty}{(q^{\frac{1}{2}-h_3}x/t_3)_\infty}$$

$$\times {}_8W_7 \left(\frac{t_1q^{h_1-h_3+\nu}}{t_3}; \frac{t_1q^{-h_3+l_1+\nu}}{t_3}, \frac{t_2q^{-h_3+l_2+\nu}}{t_3}, q^{-h_3+l_3+\nu}, \frac{t_1q^{h_1+\frac{1}{2}}}{x}, q^\nu; \frac{xq^{\frac{1}{2}-h_2}}{t_2} \right).$$

This series ${}_8W_7$ is a q -analog of the series solution ${}_2F_1 \left(\frac{x-t_1}{x-t_3}, \frac{t_2-t_3}{t_2-t_1} \right)$

(see next page).

$${}_8W_7 \xrightarrow{q \rightarrow 1} {}_2F_1$$

Taking the limit $q \rightarrow 1$, we have

$$\begin{aligned} & {}_8W_7 \left(\frac{t_1 q^{h_1 - h_3 + \nu}}{t_3}; \frac{t_1 q^{-h_3 + l_1 + \nu}}{t_3}, \frac{t_2 q^{-h_3 + l_2 + \nu}}{t_3}, q^{-h_3 + l_3 + \nu}, \frac{t_1 q^{h_1 + \frac{1}{2}}}{x}, q^\nu; \frac{x q^{\frac{1}{2} - h_2}}{t_2} \right) \\ &= \sum_{n=0}^{\infty} \frac{1 - (t_2 q^\bullet / t_3) q^{2n}}{1 - t_2 q^\bullet / t_3} \frac{(t_1 q^\bullet / t_3, t_1 q^\bullet / t_3, t_2 q^\bullet / t_3, q^\bullet, t_1 q^\bullet / x, q^\bullet)_n}{(q, q^\bullet, t_1 q^\bullet / t_2, t_1 q^\bullet / t_3, x q^\bullet / t_3, t_1 q^\bullet / t_3)_n} \left(\frac{x q^\bullet}{t_2} \right)^n \\ &\xrightarrow{q \rightarrow 1} \sum_{n=0}^{\infty} \frac{(-h_3 + l_3 + \nu; n)(\nu; n)}{(1; n)(h_1 - l_1 + 1; n)} \left(\frac{(1 - t_1/t_3)(1 - t_1/t_3)(1 - t_2/t_3)(1 - t_1/x) x}{(1 - t_1/t_2)(1 - t_1/t_3)(1 - x/t_3)(1 - t_1/t_3) t_2} \right)^n \\ &= {}_2F_1 \left(\begin{matrix} -h_3 + l_3 + \nu, \nu \\ h_1 - l_1 + 1 \end{matrix}; \frac{x - t_1}{x - t_3} \frac{t_2 - t_3}{t_2 - t_1} \right). \end{aligned}$$

Note that $(q^\alpha)_n / (1 - q)^n \xrightarrow{q \rightarrow 1} \alpha(\alpha + 1) \cdots (\alpha + n - 1) = (\alpha; n)$,
 $(X)_n \xrightarrow{q \rightarrow 1} (1 - X)^n$.

Summary

In this talk, we give integral solutions and series solutions for the variant of the q -hypergeometric equation of degree three $\mathcal{H}_3 y = 0$.

The key point is to regard this equation as a q -analog of the Riemann-Papperitz system.

There are many applications:

- q -analogs of Kummer's 24 solutions.
- A new equation that the Askey-Wilson function satisfies.
- A connection problem, and a new linear relation for the Askey-Wilson functions.

There are many future works.

- Some variants of various q -hypergeometric functions/equations.
- Special solutions for the eigenvalue problem of (first degeneration of) the Ruijsenaars-van Diejen operator.

q -analogs of Kummer's 24 solutions

Kummer's 24 solutions are the list of the series solutions for the Gauss' hypergeometric equation. For examples,

$$\begin{array}{l}
 {}_2F_1 \left(\begin{array}{c} \alpha, \beta \\ \gamma \end{array} ; x \right), \\
 x^{1-\gamma} {}_2F_1 \left(\begin{array}{c} \alpha - \gamma + 1, \beta - \gamma + 1 \\ 2 - \gamma \end{array} ; x \right), \\
 {}_2F_1 \left(\begin{array}{c} \alpha, \beta \\ \alpha + \beta - \gamma + 1 \end{array} ; 1 - x \right).
 \end{array}
 \quad
 \left.
 \begin{array}{l}
 E \left(\begin{array}{c} \alpha, \beta \\ \gamma \end{array} \right) \\
 E \left(\begin{array}{c} \alpha - \gamma + 1, \beta - \gamma + 1 \\ 2 - \gamma \end{array} \right) \\
 E \left(\begin{array}{c} \alpha, \beta \\ \alpha + \beta - \gamma + 1 \end{array} \right)
 \end{array}
 \right\}
 \begin{array}{l}
 \xrightarrow{x \mapsto 1 - x} \\
 \downarrow \times x^{1-\gamma} \\
 \leftarrow
 \end{array}$$

In the theory of q -difference equations, we can not apply some Möbius transformations. So it is difficult to find q -analogs of the above solutions directly.

By degenerating the equation $\mathcal{H}_3 y = 0$, we get the variant of the q -hypergeometric equation of degree two $\mathcal{H}_2 y = 0$ and the Heine's equation:

$$\mathcal{H}_3 y = 0 \xrightarrow{t_i \rightarrow \infty} \mathcal{H}_2 y = 0 \xrightarrow{t_j \rightarrow 0} \text{Heine.}$$

So by taking the same limit for solutions, we obtain solutions for $\mathcal{H}_2 y = 0$ and the Heine's equation systematically. For integrals, we have

$$\int \prod_{i=0}^3 \frac{(q^\bullet t_i t)_\infty}{(q^\bullet t_i t)_\infty} d_q t \rightarrow \int t^\bullet \prod_{i=0}^2 \frac{(q^\bullet t_i t)_\infty}{(q^\bullet t_i t)_\infty} d_q t \rightarrow \int t^\bullet \prod_{i=0}^1 \frac{(q^\bullet t_i t)_\infty}{(q^\bullet t_i t)_\infty} d_q t.$$

For series, we have many solutions. We summarize them in next page.

$\mathcal{H}_3 \longrightarrow \mathcal{H}_2 \longrightarrow \text{Heine}$

${}_8W_7$	${}_3\varphi_2 \left(\begin{matrix} \bullet, \bullet, \bullet t_1/x \\ \bullet, \bullet t_1/t_2 \end{matrix} ; \bullet \frac{x}{t_2} \right)$	${}_2\varphi_1 \left(\begin{matrix} \bullet, \bullet \\ \bullet \end{matrix} ; x \right)$
	${}_3\varphi_2 \left(\begin{matrix} \bullet, \bullet, \bullet x/t_1 \\ \bullet, \bullet x/t_2 \end{matrix} ; \bullet \frac{t_1}{t_2} \right)$	${}_2\varphi_1 \left(\begin{matrix} \bullet, \bullet \\ \bullet \end{matrix} ; \frac{\bullet}{x} \right)$
	${}_3\varphi_2 \left(\begin{matrix} \bullet, \bullet, \bullet t_1/t_2 \\ \bullet, \bullet x/t_2 \end{matrix} ; q \right)$	${}_3\varphi_2 \left(\begin{matrix} \bullet, \bullet, \bullet x \\ \bullet, 0 \end{matrix} ; q \right)$
	${}_3\varphi_2 \left(\begin{matrix} \bullet, \bullet, \bullet t_1/t_2 \\ \bullet, \bullet t_1/x \end{matrix} ; \bullet \frac{t_2}{x} \right)$	${}_3\varphi_2 \left(\begin{matrix} \bullet, \bullet, \bullet/x \\ \bullet, 0 \end{matrix} ; q \right)$
	${}_3\varphi_2 \left(\begin{matrix} \bullet, \bullet, \bullet t_1/x \\ \bullet, \bullet t_2/x \end{matrix} ; q \right)$	${}_2\varphi_2 \left(\begin{matrix} \bullet, \bullet \\ \bullet, \bullet x \end{matrix} ; \bullet x \right)$
${}_r\varphi_s \left(\begin{matrix} a_1, \dots, a_r \\ b_1, \dots, b_s \end{matrix} ; x \right)$	${}_3\varphi_2 \left(\begin{matrix} \bullet, \bullet, \bullet x/t_1 \\ \bullet, \bullet t_2/t_1 \end{matrix} ; q \right)$	${}_2\varphi_2 \left(\begin{matrix} \bullet, \bullet \\ \bullet, \bullet/x \end{matrix} ; \frac{\bullet}{x} \right)$
$= \sum_{n=0}^{\infty} \frac{(a_1, \dots, a_r)_n}{(q, b_1, \dots, b_s)_n} \left((-1)^n q^{\binom{n}{2}} \right)^{s+1-r} x^n.$		${}_3\varphi_2 \left(\begin{matrix} \bullet, \bullet, 0 \\ \bullet, \bullet x \end{matrix} ; q \right)$
		${}_3\varphi_2 \left(\begin{matrix} \bullet, \bullet, 0 \\ \bullet, \bullet/x \end{matrix} ; q \right)$

On the Askey-Wilson function

The very-well-poised balanced q -hypergeometric function

$${}_8W_7 \left(a; b, c, d, e, f; \frac{a^2 q^2}{bcdef} \right),$$

is well known as the Askey-Wilson function.

Some q -difference equations that the Askey-Wilson function satisfies were obtained (cf. Askey-Wilson, Ismail-Rahman).

The equation $\mathcal{H}_3 y = 0$ is different from these equations, so we get another equation for the Askey-Wilson function.

On a connection problem

We give 6 integral solutions for the equation $\mathcal{H}_3 y = 0$:

$$x^{\nu-\alpha} \int_{\sigma_1}^{\sigma_2} \frac{(q^\nu xt, q^{h_1+\frac{1}{2}}t_1t, q^{h_2+\frac{1}{2}}t_2t, q^{h_3+\frac{1}{2}}t_3t)_\infty}{(xt, q^{\nu+l_1-\frac{1}{2}}t_1t, q^{\nu+l_2-\frac{1}{2}}t_2t, q^{\nu+l_3-\frac{1}{2}}t_3t)_\infty} d_q t,$$

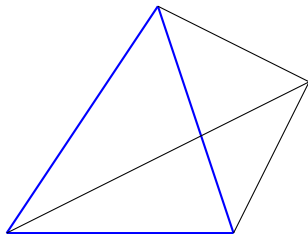
where $\sigma_1, \sigma_2 \in \{q^{\frac{1}{2}-h_1}/t_1, q^{\frac{1}{2}-h_2}/t_2, q^{\frac{1}{2}-h_3}/t_3, q^{1-\nu}/x\}$.

So there are 4 linear relations for such solutions.

We consider a connection problem:

“Find 4 linear relations for solutions of the equation $\mathcal{H}_3 y = 0$.”

By the definition $\int_{\sigma_1}^{\sigma_2} = \int_{\sigma_2}^{\sigma_2} - \int_{\sigma_1}^{\sigma_1}$ of the Jackson integral, we have $\int_{\sigma_1}^{\sigma_2} + \int_{\sigma_2}^{\sigma_3} + \int_{\sigma_3}^{\sigma_1} = 0$. Thus we get 3 relations for the above solutions.



Another one is derived by considering Mimachi's relations for the Jackson integral of the Jordan-Pochhammer type:

$$\begin{aligned} & \int_0^{q/(Ax)} t^{\alpha-1} \prod_{i=1}^M \frac{(a_i t)_\infty (Axt)_\infty}{(b_i t)_\infty (Bxt)_\infty} d_q t \\ &= \sum_{i=1}^M C_i \int_0^{q/(a_i)} t^{\alpha-1} \prod_{i=1}^M \frac{(a_i t)_\infty (Axt)_\infty}{(b_i t)_\infty (Bxt)_\infty} d_q t \\ &+ C_{M+1} \int_0^{b_1} t^\rho \prod_{i=1}^M \frac{(qt/b_i)_\infty (qt/(Bx))_\infty}{(qt/a_i)_\infty (qt/(Ax))_\infty} d_q t \quad (q^\rho = q^{-\alpha} \frac{a_1 \cdots a_M A}{b_1 \cdots b_M B}). \end{aligned}$$

Here C_1, \dots, C_{M+1} are given by some ratio of the theta function $\theta(x) = (x, q/x)_\infty$. We put the parameters as $M = 3$, $\alpha = 1$, $a_1 a_2 a_3 A = q^2 b_1 b_2 b_3 B$ (and $\rho = 1$). Then the coefficient C_{M+1} is vanished (because $C_{M+1} = \frac{\cdots \times \theta(q^\rho)}{\cdots}$).

We have

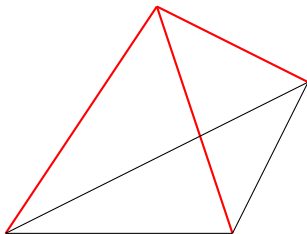
$$\int_0^{q/(Ax)} \prod_{i=1}^M \frac{(a_i t)_\infty}{(b_i t)_\infty} \frac{(Axt)_\infty}{(Bxt)_\infty} d_q t = \sum_{i=1}^3 C_i \int_0^{q/(a_i)} \prod_{i=1}^M \frac{(a_i t)_\infty}{(b_i t)_\infty} \frac{(Axt)_\infty}{(Bxt)_\infty} d_q t.$$

So we get

$$C \int_0^{q/(Ax)} \prod_{i=1}^M \frac{(a_i t)_\infty}{(b_i t)_\infty} \frac{(Axt)_\infty}{(Bxt)_\infty} d_q t = \sum_{i=1}^3 C_i \int_{q/(Ax)}^{q/(a_i)} \prod_{i=1}^M \frac{(a_i t)_\infty}{(b_i t)_\infty} \frac{(Axt)_\infty}{(Bxt)_\infty} d_q t,$$

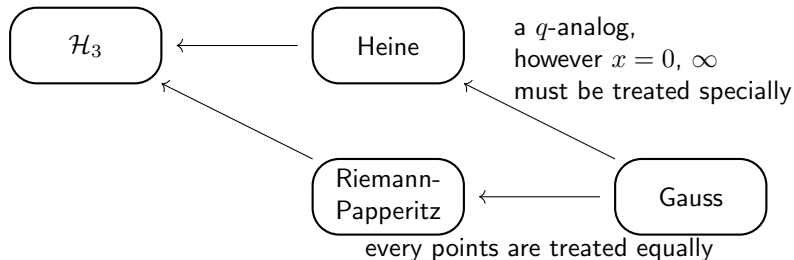
where $C = 1 + C_1 + C_2 + C_3$. The integral of the L.H.S. is not a solution for the equation $H_3 y = 0$, although the R.H.S. is a solution, so we finally find $C = 0$ and

$$\sum_{i=1}^3 C_i \int_{q/(Ax)}^{q/(a_i)} \prod_{i=1}^M \frac{(a_i t)_\infty}{(b_i t)_\infty} \frac{(Axt)_\infty}{(Bxt)_\infty} d_q t = 0.$$



Future works: a variant of the q -Appell-Lauricella system

A q -analog of the Riemann-Papperitz system has not been considered because the points $x = 0$ and ∞ are special in the theory of q -difference equations. However we could consider such a q -analog.



We can treat every point equally even in q -difference equations!

It is interesting to consider some q -hypergeometric functions with this slogan. Now I am trying for the q -Appell-Lauricella case.

The q -Appell-Lauricella system

The q -Appell-Lauricella system is defined as follows:

$$\begin{aligned} [(1 - T_i)(1 - cq^{-1}T) - x_i(1 - b_iT_i)(1 - aT)]y &= 0 \quad (1 \leq i \leq M), \\ [x_i(1 - b_iT_i)(1 - T_j) - x_j(1 - b_jT_j)(1 - T_i)]y &= 0 \quad (1 \leq i < j \leq M). \end{aligned}$$

The rank of this system is $M + 1$, and it has integral solutions and series solutions:

$$\int_C t^{\alpha-1} \frac{(qt)_\infty}{(ct/a)_\infty} \prod_{i=1}^M \frac{(b_i x_i t)_\infty}{(x_i t)_\infty} d_q t,$$
$$\varphi_D \left(\begin{matrix} a; \{b_i\} \\ c \end{matrix} ; \{x_i\} \right) = \sum_{m_1, \dots, m_M \geq 0} \frac{(a)_{m_1 + \dots + m_M}}{(c)_{m_1 + \dots + m_M}} \prod_{i=1}^M \left(\frac{(b_i)_{m_i}}{(q)_{m_i}} x_i^{m_i} \right).$$

We consider the following Jackson integral:

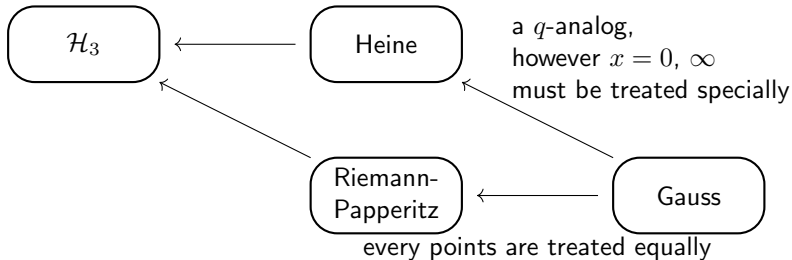
$$\int_{q/a_i}^{q/a_j} \prod_{i=1}^{M+3} \frac{(a_i t)_\infty}{(b_i t)_\infty} d_q t \quad (a_1 \cdots a_{M+3} = q^2 b_1 \cdots b_{M+3}).$$

We find some properties about this integral:

- The integral satisfies a q -difference system of rank $M + 1$.
- The integral can be transformed to some multiple q -hypergeometric series. This transformation can be derived by taking some limit for the Kajihara's transformation formula.
- A connection problem associated with the above system is solved.

We expect that many solutions for the q -Appell-Lauricella system can be obtained by degenerating the multiple series. And there are more applications, I think.

A q -analog of the Riemann-Papperitz system has not been considered because the points $x = 0$ and ∞ are special in the theory of q -difference equations. However we could consider such a q -analog.



We can treat every point equally even in q -difference equations!

Thank you very much for
your attention!